Chebyshev Polynomial Approximation for Distributed Signal Processing

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Intro

Conclusion

Motivating Application: Distributed Denoising

- Sensor network with N sensors
- Noisy signal in \mathbb{R}^N : y = x + noise
- Node n only observes y_n and wants to estimate x_n
- No central entity nodes can only send messages to their neighbors in the communication graph
- However, communication is costly
- Prior info, e.g., signal is smooth or piecewise smooth w.r.t. graph structure
 - If two sensors are close enough to communicate, their observations are more likely to be correlated



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- **2** Graph Fourier Multiplier Operators
- Chebyshev Approximation of Graph Fourier Multipliers
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- 4 Distributed Denoising Example
- 5 Summary, Ongoing Work, and Extensions

Spectral Graph Theory Notation

- Connected, undirected, weighted graph G = {V, E, W}
- Degree matrix D: zeros except diagonals, which are sums of weights of edges incident to corresponding node
- Non-normalized Laplacian: $\mathcal{L} := D W$
- Complete set of orthonormal eigenvectors and associated real, non-negative eigenvalues:

$$\mathcal{L}\chi_{\ell} = \lambda_{\ell}\chi_{\ell},$$

ordered w.l.o.g. s.t.

$$\mathbf{0} = \lambda_{\mathbf{0}} < \lambda_{1} \leq \lambda_{2} ... \leq \lambda_{N-1} := \lambda_{\max}$$



$$W = \left[\begin{array}{rrrr} 0 & .3 & .1 & 0 \\ .3 & 0 & .2 & .5 \\ .1 & .2 & 0 & .7 \\ 0 & .5 & .7 & 0 \end{array} \right]$$

$$D = \left[\begin{array}{rrrr} .4 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1.2 \end{array} \right]$$



 Values of eigenvectors associated with lower frequencies (low λ_ℓ) change less rapidly across connected vertices















 χ_{50}



■ Fourier transform: expansion of *f* in terms of the eigenfunctions of the Laplacian / graph Laplacian

Functions on the Real Line FOURIER TRANSFORM $\hat{f}(\omega) = \langle e^{i\omega x}, f \rangle = \int_{\Sigma} f(x)e^{-i\omega x} dx$

INVERSE FOURIER TRANSFORM

$$f(x) = \frac{1}{2\pi} \int\limits_{\mathbb{R}} \hat{f}(\omega) e^{i\omega x} d\omega$$

Functions on the Vertices of a Graph
GRAPH FOURIER TRANSFORM

$$\hat{f}(\ell) = \langle \chi_{\ell}, f \rangle = \sum_{n=1}^{N} f(n) \chi_{\ell}^{*}(n)$$
INVERSE GRAPH FOURIER TRANSFORM

$$f(n) = \sum_{\ell=0}^{N-1} \hat{f}(\ell) \chi_{\ell}(n)$$





• Fourier multiplier (filter) reshapes functions' frequencies:

 $\widehat{\Phi f}(\omega) = g(\omega)\widehat{f}(\omega), \text{ for every frequency } \omega$



$$f(x) \longrightarrow FT \longrightarrow \hat{f}(\omega) \longrightarrow g \longrightarrow g(\omega)\hat{f}(\omega) \longrightarrow FT \longrightarrow \Phi f(x)$$

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We can extend this to any group with a Fourier transform, including weighted, undirected graphs:

$$\Phi f = \mathsf{IFT}\Big(g(\omega)\mathsf{FT}(f)(\omega)\Big)$$



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$$T_n(x) := \cos(n \arccos(x)), \qquad T_0(x) = 1$$

$$x \in [-1, 1], \qquad T_1(x) = x$$

$$T_k(x) = 2xT_{k-1}(x) - T_{k-2}(x)$$





Source: Wikipedia.

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• Chebyshev polynomials form an orthogonal basis for $L^2\left([-1,1],\frac{dx}{\sqrt{1-x^2}}\right)$

$${\mathbb Z}$$
 Every $h \in L^2\left([-1,1], rac{dx}{\sqrt{1-x^2}}
ight)$ can be represented as

$$h(x) = \frac{1}{2}c_0 + \sum_{k=1}^{\infty} c_k T_k(x), \text{ where } c_k = \frac{2}{\pi} \int_0^{\pi} \cos(k\theta) h(\cos(\theta)) d\theta$$

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Mth order Chebyshev approximation to a continuous function on an interval provides a near-optimal approximation (in the sup norm) amongst all polynomials of degree *M*

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Mth order Chebyshev approximation to a continuous function on an interval provides a near-optimal approximation (in the sup norm) amongst all polynomials of degree *M*

SHIFTED CHEBYSHEV POLYNOMIALS

 $\ensuremath{\textcircled{}}$ To shift the domain from [-1,1] to [0,A], define

$$\overline{T}_k(x) := T_k\left(\frac{x}{\alpha} - 1\right), \text{ where } \alpha := \frac{A}{2}$$

$$\overline{T}_k(x) = \frac{2}{\alpha}(x - \alpha)\overline{T}_{k-1}(x) - \overline{T}_{k-2}(x) \quad \text{for } k \ge 2$$

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 Fast Chebyshev Approx. of a Graph Fourier Multiplier

Let $\Phi \in \mathbb{R}^{N \times N}$ be a graph Fourier multiplier with $\Phi f = \begin{bmatrix} \ddots & \ddots & \\ \vdots & \\ & (\Phi f)_N \end{bmatrix}$

Approximate Graph Fourier Multiplier Operator

$$\begin{aligned} \left(\Phi f\right)_{n} &= \sum_{\ell=0}^{N-1} g(\lambda_{\ell}) \hat{f}(\ell) \chi_{\ell}(n) = \sum_{\ell=0}^{N-1} \left[\frac{1}{2} c_{0} + \sum_{k=1}^{\infty} c_{k} \overline{T}_{k}(\lambda_{\ell}) \right] \hat{f}(\ell) \chi_{\ell}(n) \\ &\approx \sum_{\ell=0}^{N-1} \left[\frac{1}{2} c_{0} + \sum_{k=1}^{M} c_{k} \overline{T}_{k}(\lambda_{\ell}) \right] \hat{f}(\ell) \chi_{\ell}(n) \\ &= \left(\frac{1}{2} c_{0} f + \sum_{k=1}^{M} c_{k} \overline{T}_{k}(\mathcal{L}) f \right)_{n} := \left(\tilde{\Phi} f \right)_{n} \end{aligned}$$

Here,
$$\overline{T}_k(\mathcal{L}) \in \mathbb{R}^{N \times N}$$
 and $(\overline{T}_k(\mathcal{L})f)_n := \sum_{\ell=0}^{N-1} \overline{T}_k(\lambda_\ell) \hat{f}(\ell) \chi_\ell(n)$

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Question: Why do we call this a fast approximation?

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Question: Why do we call this a fast approximation?

Answer: From the Chebyshev polynomial recursion property, we have:

$$\overline{T}_{0}(\mathcal{L})f = f$$

$$\overline{T}_{1}(\mathcal{L})f = \frac{1}{\alpha}\mathcal{L}f - f, \text{ where } \alpha := \frac{\lambda_{\max}}{2}$$

$$\overline{T}_{k}(\mathcal{L})f = \frac{2}{\alpha}(\mathcal{L} - \alpha I)(\overline{T}_{k-1}(\mathcal{L})f) - \overline{T}_{k-2}(\mathcal{L})f$$

$$= \frac{2}{\alpha}\mathcal{L}\overline{T}_{k-1}(\mathcal{L})f - 2\overline{T}_{k-1}(\mathcal{L})f - \overline{T}_{k-2}(\mathcal{L})f$$

$$\tilde{\Phi}f = \frac{1}{2}c_0f + \sum_{k=1}^M c_k\overline{T}_k(\mathcal{L})f \approx \Phi f$$

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- Does not require explicit computation of the eigenvectors of the Laplacian
- Computational cost proportional to # nonzero entries in the Laplacian
- This corresponds to the number of edges in the communication graph
- Large, sparse graph $\Rightarrow \tilde{\Phi} f$ far more efficient than Φf

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Distributed Chebyshev Approximation

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$$\left(\tilde{\Phi}f\right)_n = \left(\frac{1}{2}c_0f + \sum_{k=1}^M c_k\overline{T}_k(\mathcal{L})f\right)_n$$

NODE *n*'S KNOWLEDGE:

- $(f)_n$
- 2 Neighbors and weights of edges to its neighbors

- 3 Graph Fourier multiplier $g(\cdot)$, which is used to compute c_o, c_1, \ldots, c_M
- 4 Loose upper bound on λ_{\max}

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Task: Compute $(\overline{T}_k(\mathcal{L})f)_n$, $k \in \{1, 2, ..., M\}$ in a distributed manner

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$$(\overline{T}_1(\mathcal{L})f)_n = \frac{1}{\alpha}(\mathcal{L}f)_n - (f)_n = \frac{1}{\alpha} \left[\underbrace{f}_{\alpha} \underbrace{f}$$

$$\left(\tilde{\Phi}f\right)_n = \left(\frac{1}{2}c_0f + \sum_{k=1}^M c_k\overline{T}_k(\mathcal{L})f\right)_n$$

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•
$$\left(\overline{T}_{k}(\mathcal{L})f\right)_{n} = \left(\frac{2}{\alpha}\mathcal{L}\overline{T}_{k-1}(\mathcal{L})f\right)_{n} - \left(2\overline{T}_{k-1}(\mathcal{L})f\right)_{n} - \left(\overline{T}_{k-2}(\mathcal{L})f\right)_{n}$$

• To get $(\overline{T}_2(\mathcal{L})f)_n$, suffices to compute $(\mathcal{L}\overline{T}_1(\mathcal{L})f)_n = \overline{[\overline{T}_2 \cup 0 \cup \overline{T}_3 \cup 0 \cup \overline{T}_4 \cup 0 \cup \overline{T}_4]}$, $\overline{T}_{i,i,0}$

$$\left(\tilde{\Phi}f\right)_n = \left(\frac{1}{2}c_0f + \sum_{k=1}^M c_k\overline{T}_k(\mathcal{L})f\right)_n$$

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$$(\overline{T}_1(\mathcal{L})f)_n = \frac{1}{\alpha}(\mathcal{L}f)_n - (f)_n = \frac{1}{\alpha} \left[\underbrace{f_{\alpha}(\mathcal{L}) \circ \mathcal{L}_{\alpha}(\mathcal{O})}_{\mathcal{L}_{\alpha}(\mathcal{O})} \right]_{f} - (f)_n$$

$$\left(\overline{T}_{k}(\mathcal{L})f\right)_{n} = \left(\frac{2}{\alpha}\mathcal{L}\overline{T}_{k-1}(\mathcal{L})f\right)_{n} - \left(2\overline{T}_{k-1}(\mathcal{L})f\right)_{n} - \left(\overline{T}_{k-2}(\mathcal{L})f\right)_{n}$$

2*M*|*E*| scalar messages

• To get $(\overline{T}_2(\mathcal{L})f)_n$, suffices to compute $(\mathcal{L}\overline{T}_1(\mathcal{L})f)_n = 1$ (1.1)

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Prior: signal is smooth w.r.t the underlying graph structure

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- Prior: signal is smooth w.r.t the underlying graph structure
- Regularization term: $f^{\mathrm{T}}\mathcal{L}f = \frac{1}{2}\sum_{n \in V}\sum_{m \sim n} w_{m,n} [f(m) f(n)]^2$

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 Distributed Denoising - Method 1
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- $f^{T}\mathcal{L}f$ is small when signal f has similar values at neighboring vertices connected by an edge with a large weight
- Distributed regularization problem:

$$\underset{f}{\operatorname{argmin}} \frac{\tau}{2} \|f - y\|_{2}^{2} + f^{\mathrm{T}} \mathcal{L} f$$
(1)

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 Distributed Denoising - Method 1
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- Prior: signal is smooth w.r.t the underlying graph structure
- Regularization term: $f^{\mathrm{T}}\mathcal{L}f = \frac{1}{2}\sum_{n \in V}\sum_{m \sim n} w_{m,n} [f(m) f(n)]^2$

 $\square f^{T}\mathcal{L}f = 0$ iff f is constant across all vertices

- Distributed regularization problem:

$$\underset{f}{\operatorname{argmin}} \frac{\tau}{2} \|f - y\|_{2}^{2} + f^{\mathrm{T}} \mathcal{L} f$$
(1)

Proposition

The solution to (1) is given by Ry, where R is a graph Fourier multiplier operator with multiplier $g(\lambda_{\ell}) = \frac{\tau}{\tau + 2\lambda_{\ell}}$.

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Distributed Chebyshev Approximation

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Distributed Denoising Illustrative Example

- Graph analog to low-pass filtering
- Modify the contribution of each Laplacian eigenvector

- Use Chebyshev approximation to compute *R̃y* in a distributed manner
- Over 1000 experiments, average mean square error reduced from 0.250 to 0.013





Original Signal

Noisy Signal

Denoised Signal

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Distributed Chebyshev Approximation

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Unions of Graph Fourier Multipliers

- So far, just a single graph Fourier multiplier
- Can easily extend this to unions of graph Fourier multipliers:



Multiplier Operators Chebyshev Approximation Distributed Denoising Conclusion Unions of Graph Fourier Multipliers Ν $\left[\begin{array}{c|c} \mathbf{\Phi}_{1} \\ \hline \\ \mathbf{\Phi}_{2} \\ \hline \\ \mathbf{\Phi}_{2} \end{array}\right] \quad \mathbf{f} \quad \left| \begin{array}{c} \mathbf{F} \\ \mathbf$ So far, just a single graph Fourier multiplier Can easily extend this Nn · - Nn to unions of graph Fourier multipliers: (Φ_ηf)₁

EXAMPLE: SPECTRAL GRAPH WAVELET TRANSFORM (HAMMOND ET AL., 2011)

 ${\it I\!\!I} \ g_j(\lambda_\ell) = g(t_j\lambda_\ell)$ for $j\in\{1,2,\ldots,\eta-1\}$, where $g(\cdot)$ is a band-pass filter

 \square $g_{\eta}(\cdot)$ is a low-pass filter; coefficients represent low frequency content of signal



■ Prior: signal is p.w. smooth w.r.t. graph ⇔ SGWT coefficients sparse

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- Regularize via LASSO (Tibshirani, 1996):

$$\min_{a} \ \frac{1}{2} \|y - W^* a\|_2^2 + \mu \|a\|_1$$

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Solve via iterative soft thresholding (Daubechies et al., 2004):

$$a^{(k)} = S_{\mu\tau} \Big(a^{(k-1)} + \tau W \Big(y - W^* a^{(k-1)} \Big) \Big), \ k = 1, 2, \dots$$

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- D-LASSO (Mateos et al., 2010) solves in distributed fashion, but requires 2|E| messages of length N(J+1) at each iteration
- Communication cost of Chebyshev polynomial approximation:
 - One computation of $\tilde{W}y$ (2M|E| messages of length 1)

 - Image: One final computation of $\tilde{W}^* \tilde{a}$ to recover signal (2M|E| messages of length J + 1)

Distributed Denoising - Method 2

- $\blacksquare \ \ \mathsf{Prior: \ signal \ is \ p.w. \ smooth \ w.r.t. \ graph \Leftrightarrow \mathsf{SGWT \ coefficients \ sparse}$
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Solve via iterative soft thresholding (Daubechies et al., 2004):

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- D-LASSO (Mateos et al., 2010) solves in distributed fashion, but requires 2|E| messages of length N(J + 1) at each iteration
- Communication cost of Chebyshev polynomial approximation:
 - One computation of $\tilde{W}y$ (2M|E| messages of length 1)
 - At each soft thresholding iteration, distributed computation of $\tilde{W}\tilde{W}^*a^{(k-1)}$ (2M|E| messages of length J + 1 and 2M|E| messages of length 1)
 - Image: One final computation of $\tilde{W}^* \tilde{a}$ to recover signal (2M|E| messages of length J + 1)
- Key takeaway: communication workload only scales with network size through |*E*|, otherwise independent of *N*

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- Graph Fourier muliplier operators are the graph analog of filter banks
 - They reshape functions' frequencies through multiplication in the graph Fourier domain
- A number of distributed signal processing tasks can be represented as applications of graph Fourier multiplier operators
- We approximate graph Fourier multipliers by Chebyshev polynomials
- The recurrence relations of the Chebyshev polynomials make the approximate operators readily amenable to distributed computation
- The communication required to perform distributed computations only scales with the size of the network through the number of edges in the communication graph
- The proposed method is well-suited to large-scale sensor networks with sparse communication graphs

- Reviewer: "This seems to be a very interesting technique looking for a problem"
 - Other possible applications we are working on include distributed smoothing, deconvolution, classification, and learning
 - More thorough comparisons of communication costs with alternative distributed methods for these applications

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 - Extension: use the eigenvectors of other symmetric positive-semidefinite matrices as bases

Ongoing Work and Extensions

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 - Other possible applications we are working on include distributed smoothing, deconvolution, classification, and learning
 - More thorough comparisons of communication costs with alternative distributed methods for these applications
- Extension: use the eigenvectors of other symmetric positive-semidefinite matrices as bases
- Robustness issues
 - Sensitivity to quantization and communication noise how do they propagate?
 - $\ensuremath{\textcircled{\square}}$ Effect of a sensor node dropping out of the network or losing synchronicity

Further Reading

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