

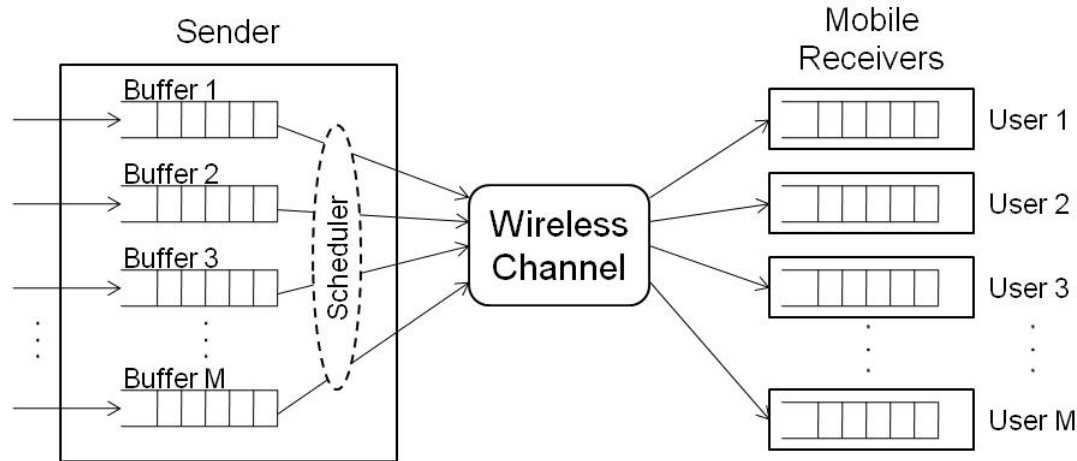
# Energy-Efficient Transmission Scheduling for Wireless Media Streaming with Strict Underflow Constraints

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# Wireless Media Streaming



## Key Features

- Single source transmitting media streams to multiple users over a shared wireless channel
- Available data rate of the channel varies with time and from user to user

## Desirable Operating Characteristics

- Provide high playout quality for all users
- Maximize the number of users that can be supported
- Limit interference to other senders and their associated mobiles
- Extend system lifetime (when sender is a mobile device)

## Opportunistic Scheduling

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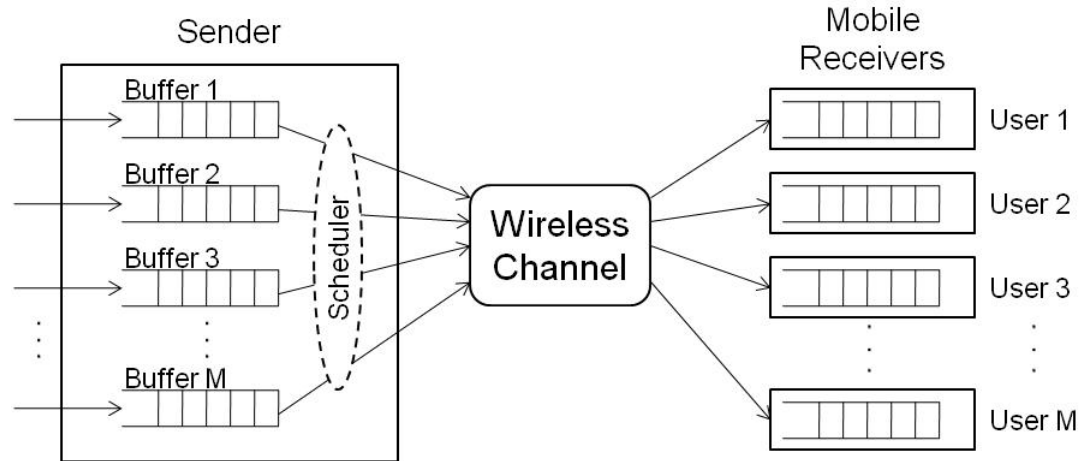
- Exploit temporal and spatial variation of the channel by transmitting to users with the best available data rates
  - “Multiuser diversity gain,” introduced in context of analogous *uplink* problem
- Consider a notion of fairness
  - Temporal fairness
  - Proportional fairness
  - Utilitarian fairness
  - ...
- Our approach
  - Playout quality is closely linked to receiver buffer underflow
  - Accordingly, we introduce strict buffer underflow constraints as our notion of fairness

## Outline

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- **Problem Description and Formulation**
- Single User Case
- Multiple Users Case
- Future Work and Concluding Remarks

## Problem Description



### Timing in Each Slot

- Transmitter learns each channel's state through a feedback channel
- Transmitter allocates some amount of power (possibly zero) for transmission to each user
  - Total power allocated in any slot cannot exceed a power constraint,  $P$
- Transmission and reception
- Packets removed/purged from each receiver's buffer for playing

## Problem Description (cont.)

### Two Control Objectives

- Avoid underflow, so as to maintain playout quality
- Minimize system-wide power consumption

### Key Modeling Assumptions

- Sender always has data to transmit to each receiver
- Receivers have infinite buffers
- Slot duration within channel coherence time (condition constant over slot)
- Each user's channel condition is *i.i.d.*
- Transmitter knows precisely the packet requirements of each user in each time slot (as it knows the encoding and decoding schemes)
- Each user's per slot consumption of packets is constant over time,  $d^m$
- Packets transmitted during a slot arrive in time to be played in the same slot
- The available power  $P$  is always sufficient to transmit packets to cover one slot of playout for each user

# Finite and Infinite Horizon Problem Formulation

## Cost Structure, Information State, and Action Space

### Cost Structure

- Transmission costs
  - Assume a linear power-rate function
  - $C_n^m$  is a random variable describing power consumption per unit of data transmitted to user  $m$  at time  $n$  (including retransmissions)
  - Realizations of  $C_n^m$  lie in  $(0, c_{MAX}^m]$
- Holding costs
  - Per packet per slot holding cost  $h^m$  assessed on all packets remaining in user  $m$ 's receiver buffer after playout consumption
  - Technical assumption – can take  $h^m$  arbitrarily small

### Information State

- $X_n = (X_n^1, X_n^2, \dots, X_n^M)^T$  = vector of receiver buffer queue lengths at time  $n$
- $C_n = (C_n^1, C_n^2, \dots, C_n^M)^T$  = vector of channel conditions for slot  $n$

### Action Space

- Defined in terms of  $\mathbf{y}$ , receiver buffer queue levels **after** transmission
- Must satisfy strict underflow constraints and system-wide power constraint
- $\mathcal{A}(\mathbf{x}, \mathbf{c}) := \left\{ \mathbf{y} \in \mathbb{R}_+^M : \max(\mathbf{x}, \mathbf{d}) \preceq \mathbf{y} \text{ and } \mathbf{c}^T(\mathbf{y} - \mathbf{x}) \leq P \right\}$

# Finite and Infinite Horizon Problem Formulation

## System Dynamics, Optimization Criteria, and Optimization Problems

### System Dynamics

- $X_{n-1} = Y_n - d$
- $C_{n-1}$  generated as *i.i.d.* random variable

### Optimization Criteria

- Finite horizon expected discounted cost criterion:

$$J_N^\pi := \mathbb{E}^\pi \left\{ \sum_{m=1}^M \sum_{t=1}^N \alpha^{N-t} \cdot \left\{ C^m \cdot (Y_t^m - X_t^m) + h^m \cdot (Y_t^m - d^m) \right\} \mid \mathcal{F}_N \right\}$$

- Infinite horizon expected discounted cost criterion:

$$J_\infty^\pi = \lim_{N \rightarrow \infty} J_N^\pi$$

### Optimization Problems

$$\begin{aligned} & \min_{\pi \in \Pi} J_N^\pi \quad \left( \text{or} \quad \min_{\pi \in \Pi} J_\infty^\pi \right) \\ \text{s.t.} \quad & \sum_{m=1}^M C_n^m \cdot (Y_n^m - X_n^m) \leq P, \quad \forall n \quad \text{and} \\ & Y_n^m \geq \max(X_n^m, d^m), \quad \forall m, \forall n. \end{aligned}$$



## Relation to Inventory Theory

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- In inventory language, our problem is a multi-period, multi-item, discrete time inventory model with random ordering prices, deterministic demand, and a budget constraint
  - Items / goods → mobile receivers
  - Random ordering prices → random channel conditions
  - Deterministic demand → users' packet requirements for playout
  - Budget constraint → transmitter's power constraint
- To our knowledge, this model has not been studied, but there is some related work
  - Single item inventory models with random ordering prices
    - B. G. Kingsman, 1969
    - K. Golabi, 1985
  - Single and multiple item inventory models with stochastic demands and deterministic ordering prices
    - R. Evans, 1967
    - A. Federgruen and P. Zipkin, 1986
    - G. A. DeCroix, 1998



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# Single User Case

## Finite Horizon Problem

### *Dynamic Program*

$$V_n(x, c) = \min_{\max(x, d) \leq y \leq x + \frac{P}{c}} \{ c \cdot (y - x) + h \cdot (y - d) + \alpha \cdot \mathbb{E}[V_{n-1}(y - d, C)] \}$$

$$V_0(x, c) = 0, \quad \forall x \in \mathbb{R}_+, \forall c \in \mathcal{C} = [c_{\min}, c_{\max}]$$

- Uncountable state space and uncountable action space
- Computationally intractable

# Single User Case

## Finite Horizon Problem

### ***Equivalent Dynamic Programming Equation***

$$\begin{aligned} V_n(x, c) &= \min_{\max(x, d) \leq y \leq x + \frac{P}{c}} \{c \cdot (y - x) + h \cdot (y - d) + \alpha \cdot \mathbb{E}[V_{n-1}(y - d, C)]\} \\ &= -c \cdot x - h \cdot d + \min_{\max(x, d) \leq y \leq x + \frac{P}{c}} \{y \cdot (c + h) + \alpha \cdot \mathbb{E}[V_{n-1}(y - d, C)]\} \\ &= -c \cdot x - h \cdot d + \min_{\max(x, d) \leq y \leq x + \frac{P}{c}} \{g_n(y, c)\} \end{aligned}$$

- If action space were independent of  $x$ , we would have a base-stock policy
- Instead, we get a modified base-stock policy

# Single User Case

## Structure of Optimal Policy

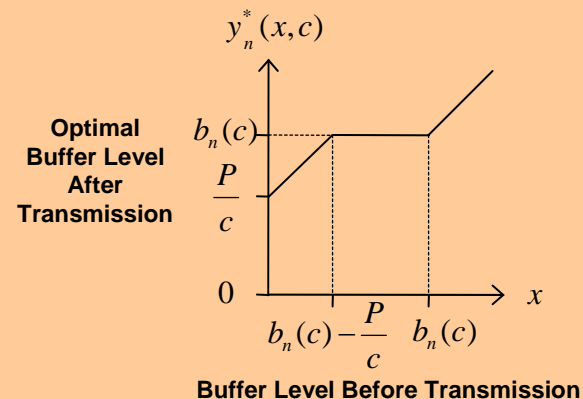
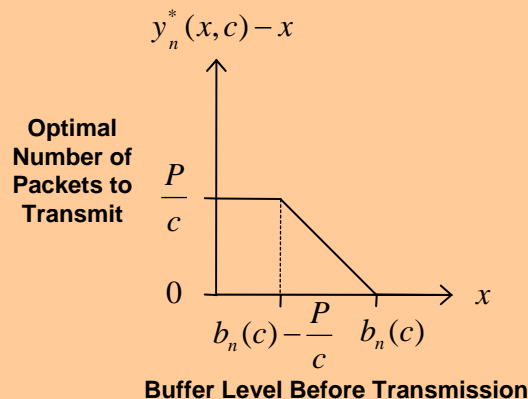
### Theorem

For every  $n \in \{1, 2, \dots, N\}$  and  $c \in \mathcal{C}$ , there exists a *critical number*,  $b_n(c)$ , such that the optimal control strategy is given by  $\pi^* = \{y_N^*, y_{N-1}^*, \dots, y_1^*\}$ , where

$$y_n^*(x, c) := \begin{cases} x, & \text{if } x \geq b_n(c) \\ b_n(c), & \text{if } b_n(c) - \frac{P}{c} \leq x \leq b_n(c) \\ x + \frac{P}{c}, & \text{if } x < b_n(c) - \frac{P}{c} \end{cases} .$$

Furthermore, for a fixed  $n$ ,  $b_n(c)$  is nonincreasing in  $c$ , and for a fixed  $c$ :  $N \cdot d \geq b_N(c) \geq b_{N-1}(c) \geq \dots \geq b_1(c) = d$ .

### Graphical representation of optimal transmission policy



# Single User Case

## Structure of Optimal Policy

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### Question:

**Can we find  
explicit form for  
critical numbers?**

# Single User Case

## Complete Characterization of Optimal Policy

### Additional Technical Assumptions

- Set of possible channel conditions is finite:  $\mathcal{C} = \{c_1, c_2, \dots, c_K\}$
- Receiver buffer empty at beginning of time horizon
- $L(c) := P/(c \cdot d)$  is an integer

### Thresholds & Critical Numbers

- We can define recursively a set of thresholds
- From these thresholds, we can find the critical numbers
- This process is far simpler computationally than solving the dynamic program

# Single User Case

## Infinite Horizon Problem

- Infinite horizon optimal policy is natural extension of finite horizon optimal policy
- Stationary optimal policy characterized by critical numbers  $b_\infty(c)$ , where

$$b_\infty(c) := \lim_{n \rightarrow \infty} b_n(c)$$

- Again, we have a modified base-stock policy:

$$y_\infty^*(x, c) := \begin{cases} x, & \text{if } x \geq b_\infty(c) \\ b_\infty(c), & \text{if } b_\infty(c) - \frac{P}{c} \leq x \leq b_\infty(c) \\ x + \frac{P}{c}, & \text{if } x < b_\infty(c) - \frac{P}{c} \end{cases} .$$





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## Multiple Users Case

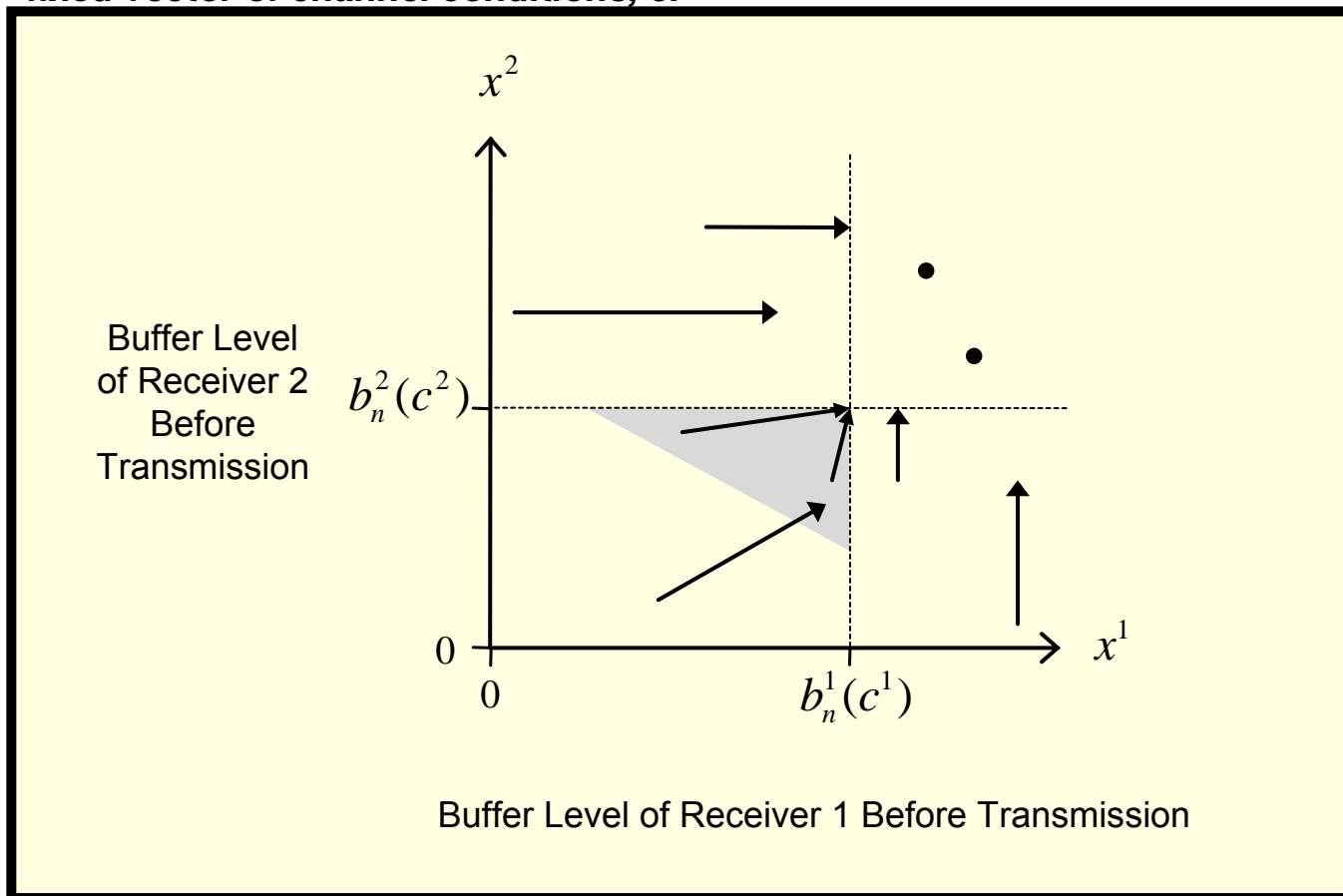
### Conjecture Based on Numerical Experiments

#### Single user optimal policy appears to extend in following manner:

- For each vector of channel conditions  $\mathbf{c}$  at time  $n$ , there exists a vector of critical numbers with one critical number for each user
  - Each user's critical number  $b_n^m$  depends only on its current channel condition  $c^m$ 
    - Independent of its own current buffer level
    - Independent of other users' current buffer levels
    - Independent of other users' current channel conditions
- Optimal policy is characterized by the critical numbers
  - Do not transmit packets to any user whose current buffer level exceeds its critical number
  - If possible to bring all users up to critical number, do so
  - If power constraint prevents transmitter from bringing all users up to their critical numbers, it should allocate the full power  $P$  to different users
    - Yet to determine optimal allocation between users

# Multiple Users Case Example

**Structure of the optimal policy for the two-user case in slot  $n$ , with a fixed vector of channel conditions,  $c$ .**





## Outline

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## Current and Future Work

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- Prove structure of optimal policy in multiple users case
- Identify low-complexity sub-optimal policies that perform well in multi-user case when power constraint prevents transmitting up to all critical numbers
- Performance analysis
- Derive alternate condition for complete characterization of optimal policy in single user case
  - Set the maximum number of packets that can be transmitted in a slot to  $\left\lfloor \frac{P}{c \cdot d} \right\rfloor \cdot d$
- Relax *i.i.d.* assumption, and examine Markovian channel
- Explore the possibility of dropping resource-draining users and determining when new users can be admitted

## Concluding Remarks

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- Considered problem of transmitting media streams over a shared wireless channel in a manner that prevents receivers' buffers from emptying
- In single user case, showed optimal transmission schedule is a modified base-stock policy under both finite and infinite horizon discounted expected cost criteria
- Numerical experiments suggest similar structure for multi-user case
- Modified base-stock policies have nice feature that they are easily implementable